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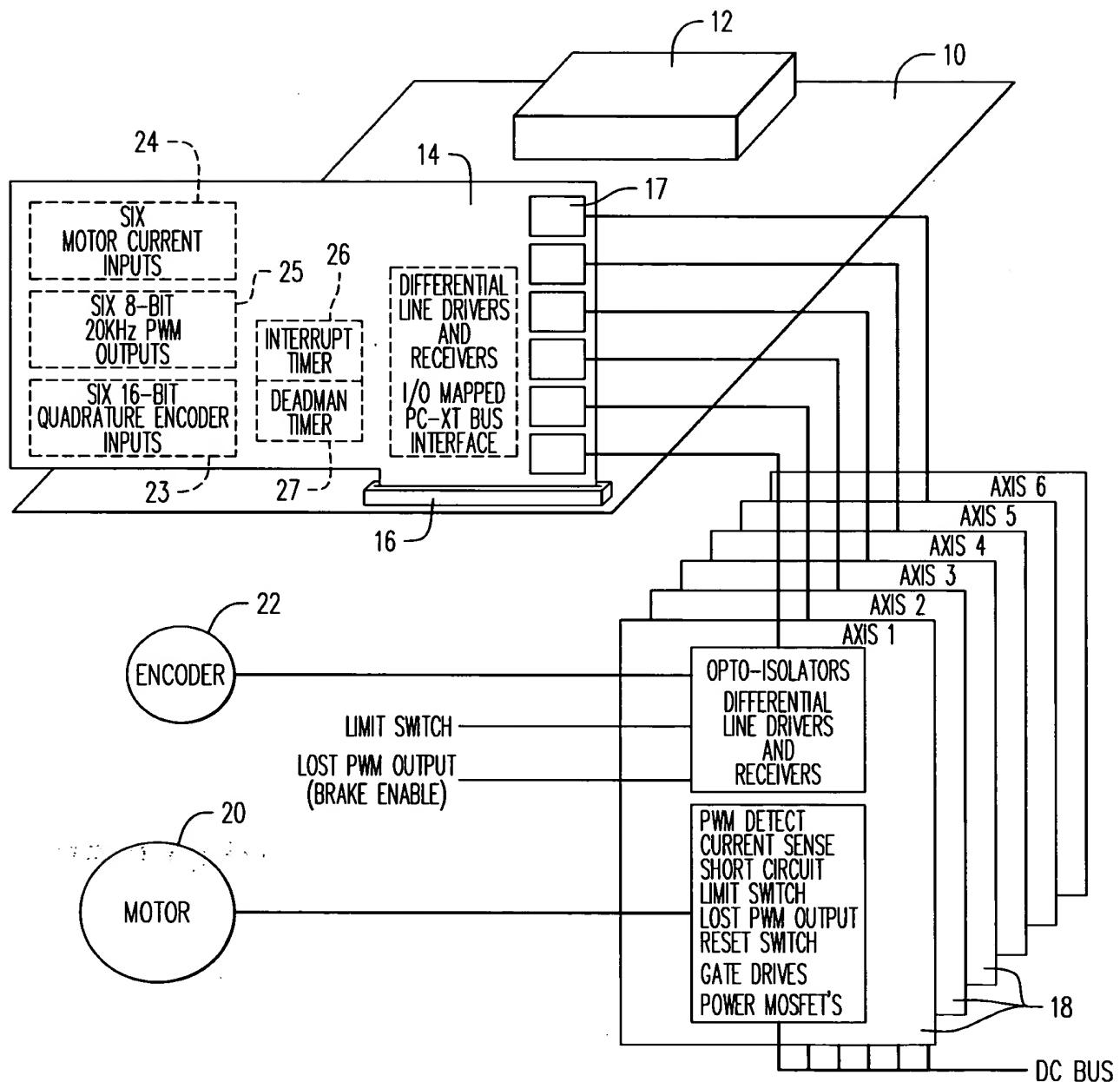
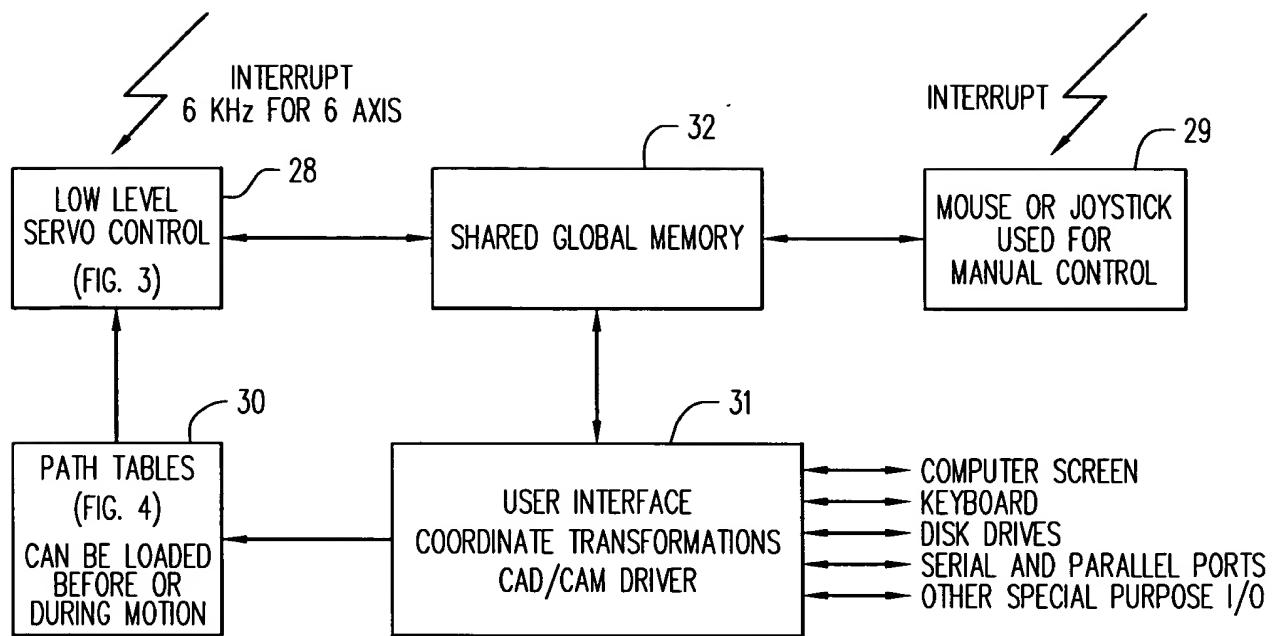
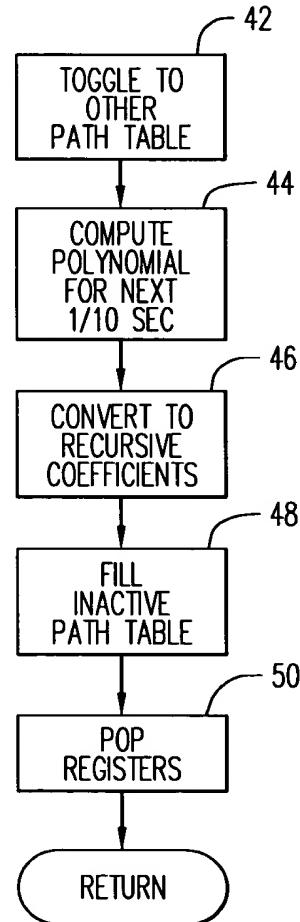


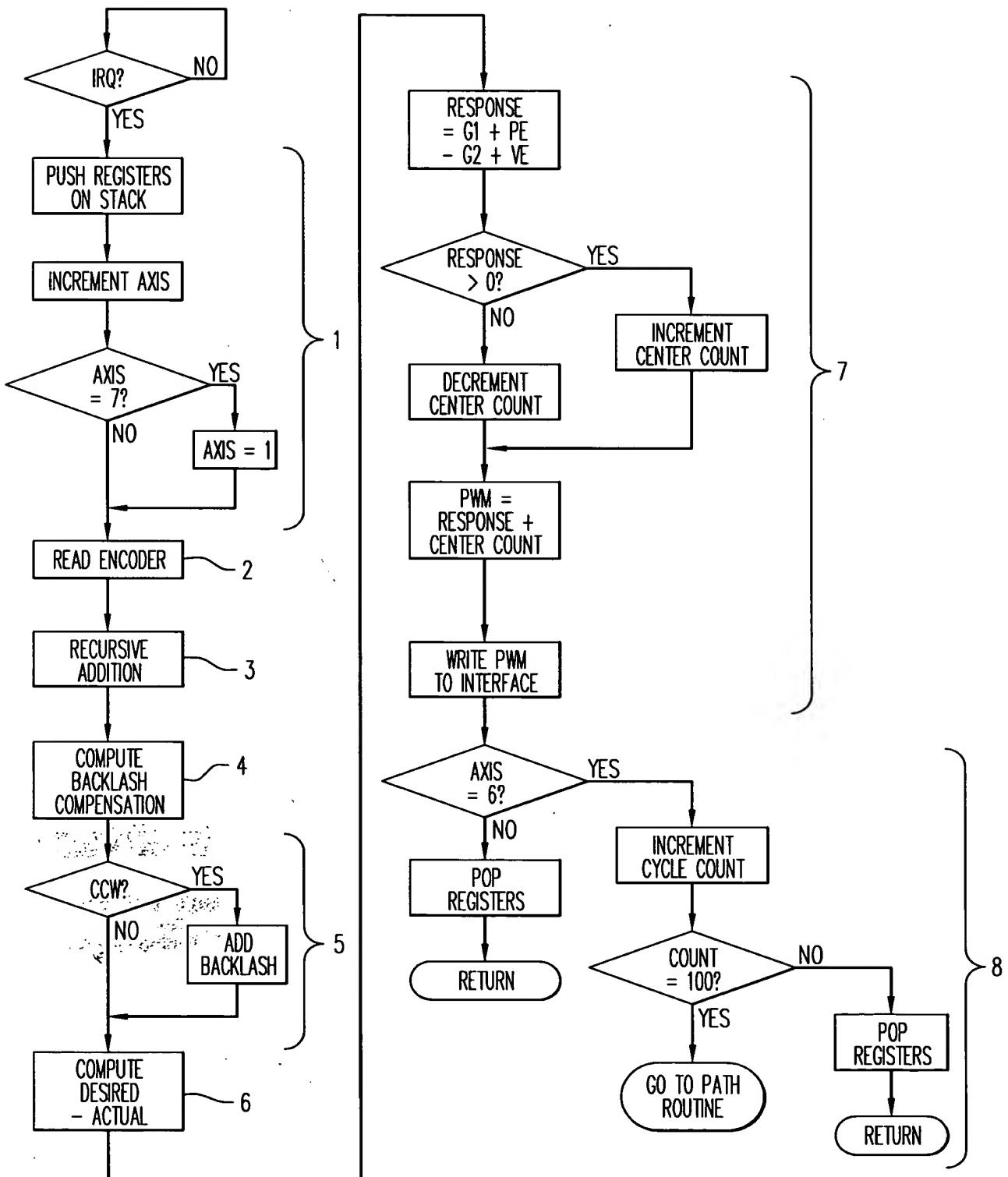
FIG. 1



**FIG. 2**

**FIG. 4**





**FIG. 3**

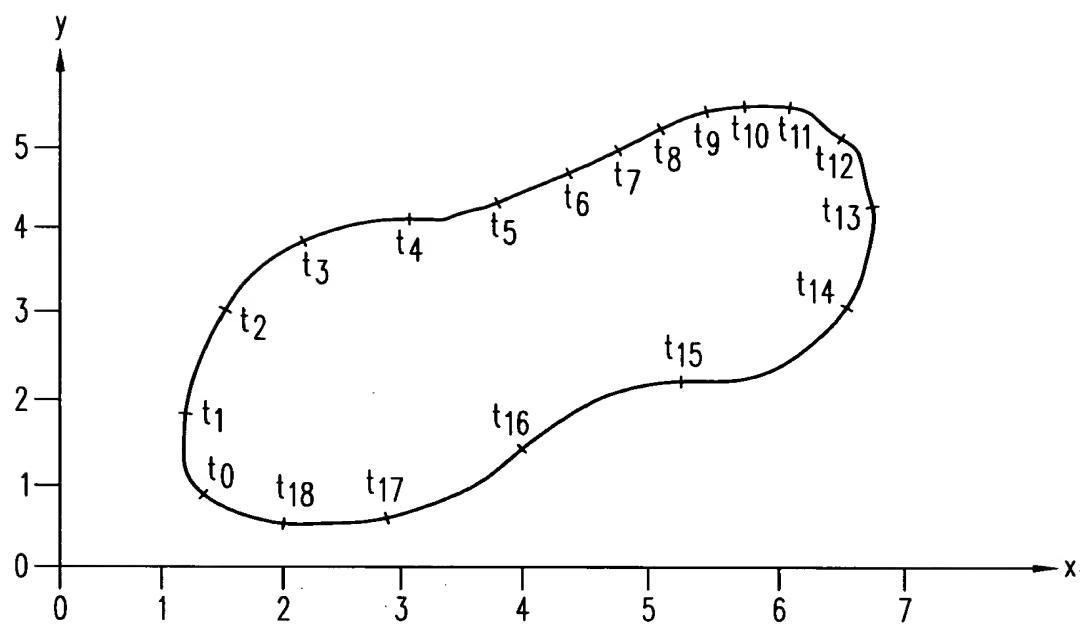
**FIG. 5**

PATH TABLE 1

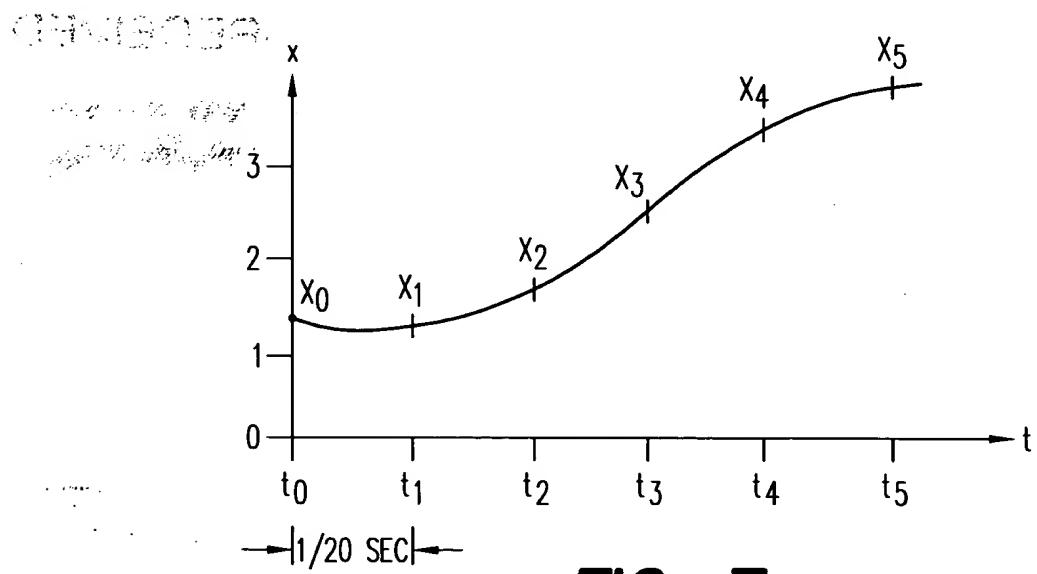
POSITION 34		VELOCITY 36		ACCELERATION 38		JERK 40	
AXIS							
1	W . F	W . F	W . F	W . F	W . F	W . F	W . F
2	W . F	W . F	W . F	W . F	W . F	W . F	W . F
3	W . F	W . F	W . F	W . F	W . F	W . F	W . F
4	W . F	W . F	W . F	W . F	W . F	W . F	W . F
5	W . F	W . F	W . F	W . F	W . F	W . F	W . F
6	W . F	W . F	W . F	W . F	W . F	W . F	W . F

PATH TABLE 2

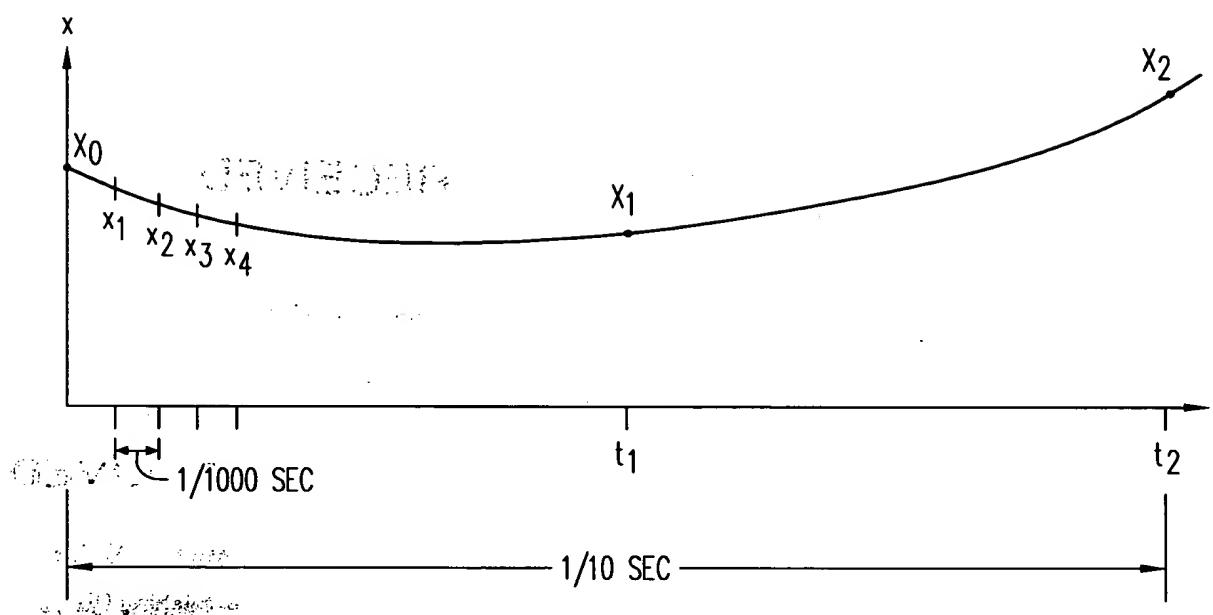
1	W . F	W . F	W . F	W . F
2	W . F	W . F	W . F	W . F
3	W . F	W . F	W . F	W . F
4	W . F	W . F	W . F	W . F
5	W . F	W . F	W . F	W . F
6	W . F	W . F	W . F	W . F



**FIG. 6**



**FIG. 7**



**FIG. 8**